

THE DISCREPANCY FUNCTION IN TWO DIMENSIONS

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ABSTRACT. Let \mathcal{A}_N be an N -point set in the unit square and consider the Discrepancy function

$$D_N(\vec{x}) := \#(\mathcal{A}_N \cap [0, \vec{x})) - N|[0, \vec{x})|,$$

where $\vec{x} = (x_1, x_2) \in [0, 1]^2$, $[0, \vec{x}) = [0, x_1) \times [0, x_2)$, and $|[0, \vec{x})|$ denotes the Lebesgue measure of the rectangle. This is the difference between the actual number of points of \mathcal{A}_N in such a rectangle and the expected number of points - Nx_1x_2 - in the rectangle. A basic theme of discrepancy theory is to study the "size" of this function in terms of N . It turns out that no matter how the N points are selected, their distribution must be far from uniform, i.e. the discrepancy function must be "large". In this talk I will give an overview of some classical results in discrepancy theory that quantify the principle described above. I will also give an example of an *extremal* set for Discrepancy, in particular the van der Corput point set. Finally, if time permits, I will discuss some size estimates for the discrepancy function obtained in a *joint work* with D. Bilyk, M. Lacey and A. Vagharshakyan . For example we prove that

$$\|D_N\|_{\text{BMO}} \gtrsim (\log N)^{1/2}.$$

This estimate is sharp. For the van der Corput set, we have $\|D_N\|_{\text{BMO}} \lesssim (\log N)^{1/2}$, whenever $N = 2^n$ for some positive integer n .

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